

Branch-and-Bound with Predictions for Variable Selection

Yatharth Dubey

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VARIABLE SELECTION

Certifying bounds in pure binary ILP:

$$\max \{cx : x \in P \cap \{0,1\}^n\} \leq v^*$$

where $P = \{x \in [0,1]^n : Ax \leq b\}$, $A \in \mathbb{Z}^{m \times n}$, $b \in \mathbb{Z}^m$

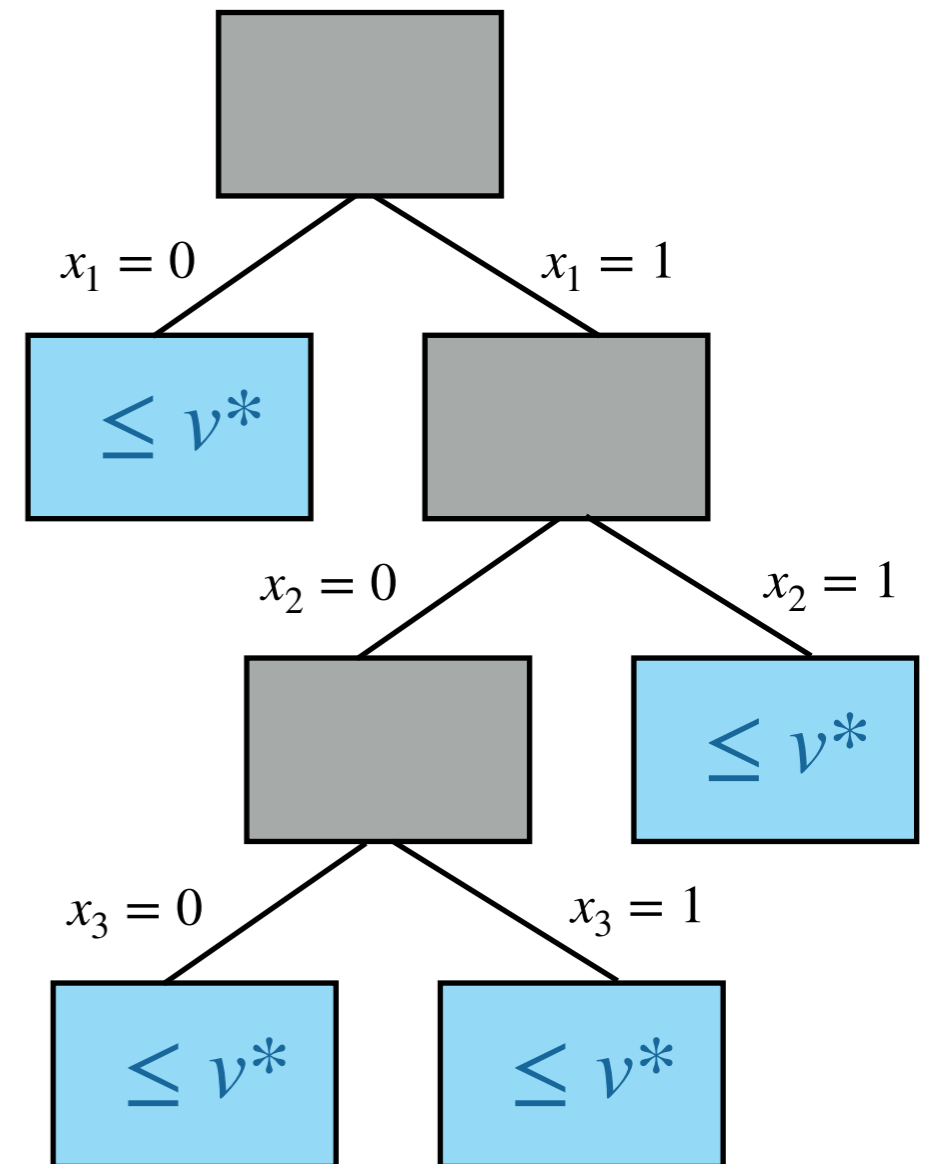
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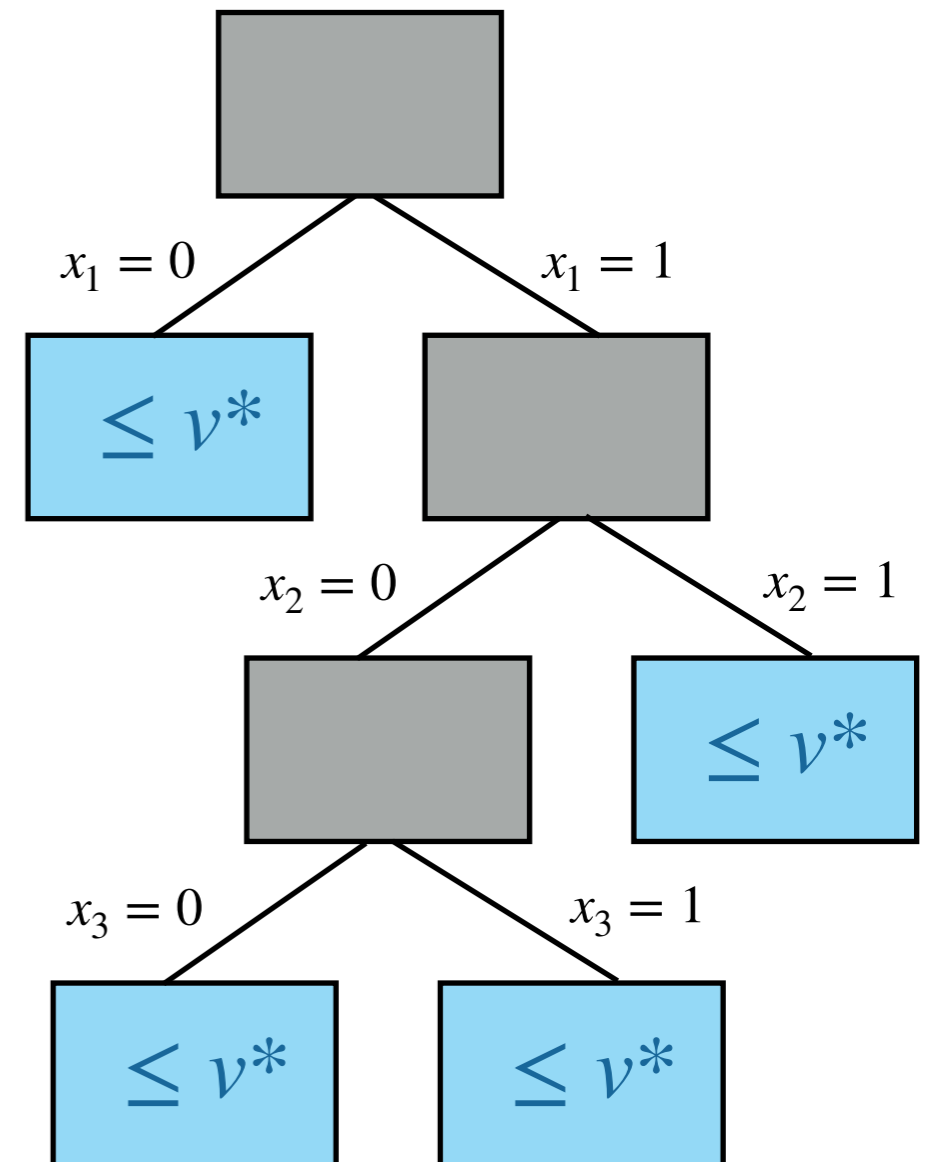
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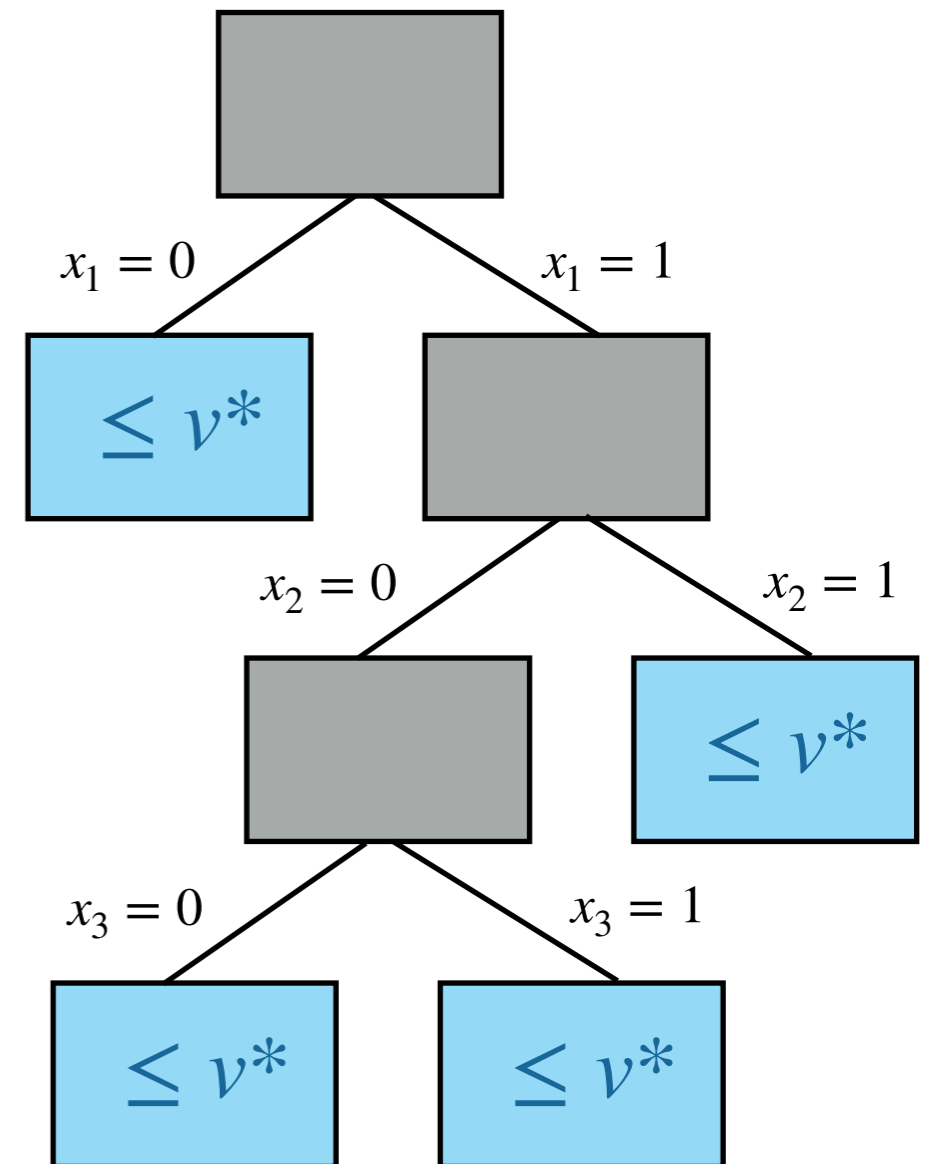
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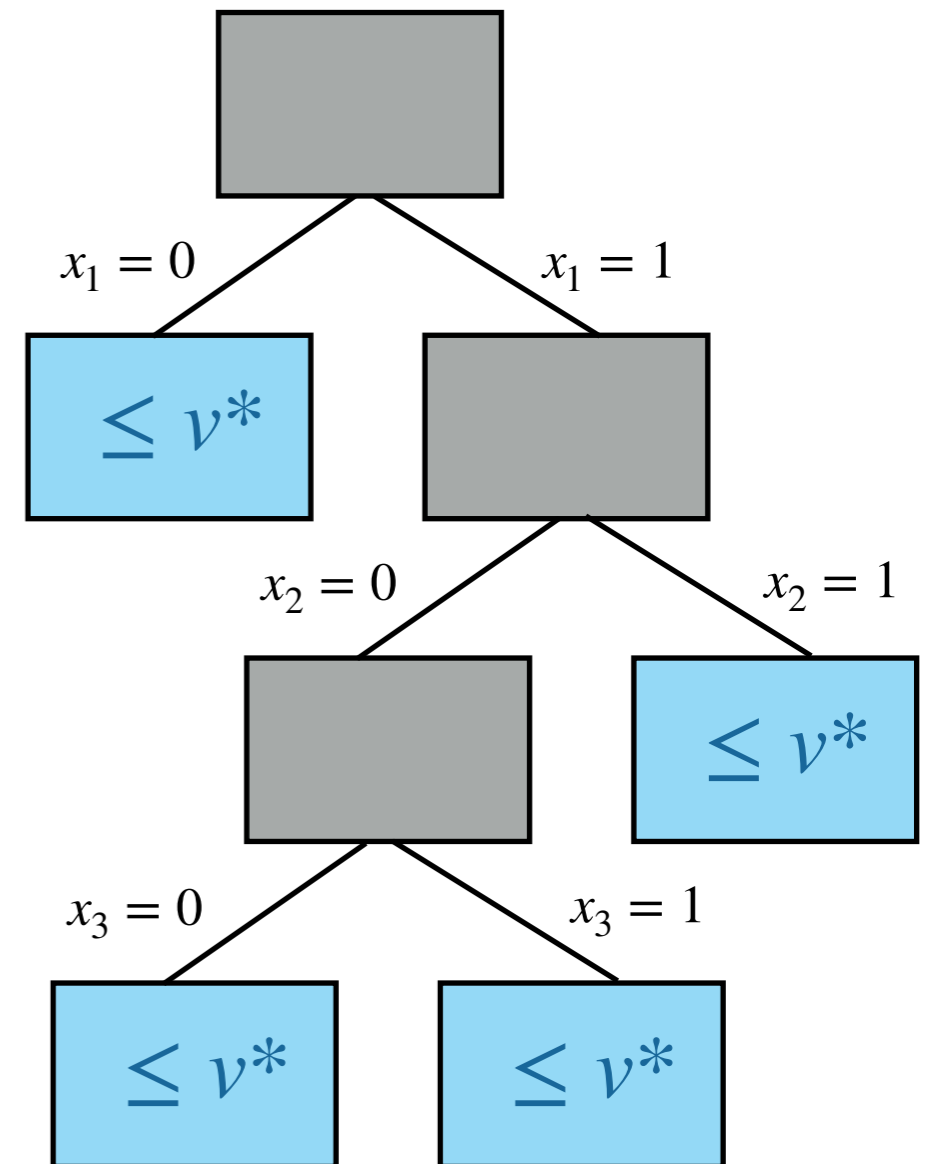
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But... is strong branching the expert we should be imitating?

Next, we give a framework through which we can think about this question

Strong Branching: (below $v(S)$ is the LP optimal value of subproblem S)

$$\text{At subproblem } S \text{ branch on } j^* = \arg \max_{j \in C \setminus n} \underbrace{(v(S) - v(S_{j=0}))}_{\Delta_j^-} + \underbrace{(v(S) - v(S_{j=1}))}_{\Delta_j^+}$$

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At subproblem S branch on $j^* = \arg \max_{j \in C \setminus n} (v(S) - v(S_{j=0})) + (v(S) - v(S_{j=1}))$

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But branch-and-bound actually admits an **optimal recurrence relation**:

$$\theta(S, v^*) = \min_{j \in [n]} \theta(S_{j=0}, v^*) + \theta(S_{j=1}, v^*)$$

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This suggests branching on $j^* = \arg \min_{j \in [n]} \theta(S_{j=0}, v^*) + \theta(S_{j=1}, v^*)$

(which would **obtain a BB tree of minimum size**)

ESTIMATING THE OPTIMAL RULE

Optimal rule: at subproblem S , branch on $j^* = \arg \min_{j \in [n]} \theta(S_{j=0}, v^*) + \theta(S_{j=1}, v^*)$

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Question 1: How does the quality of the estimate affect the size of the resulting tree? If $\hat{\theta}(S, v^*) \approx \theta(S, v^*)$ will we get a near-minimum-size tree?

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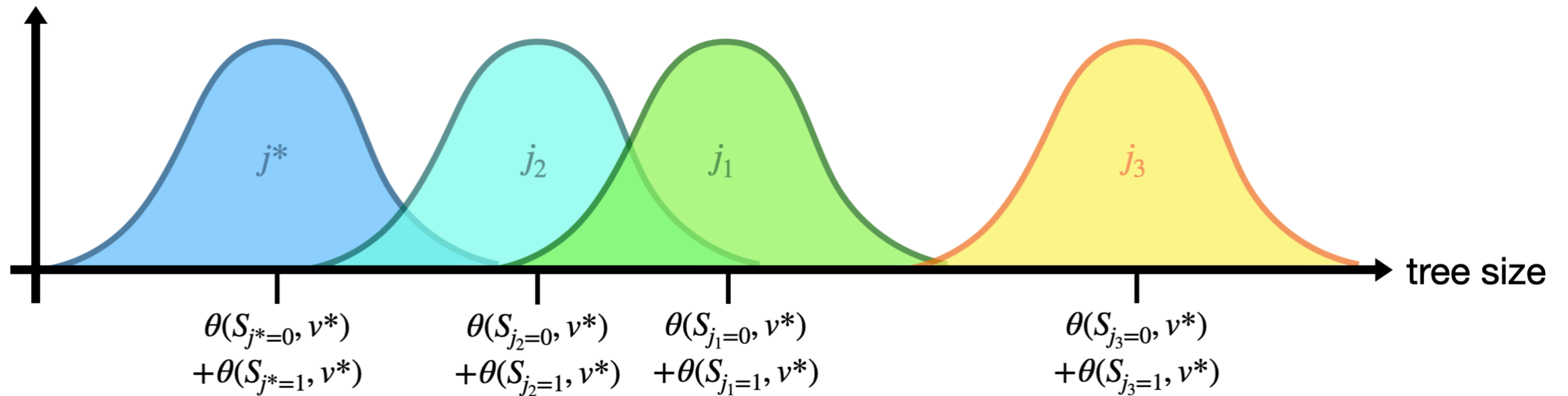
Question 1: How does the quality of the estimate affect the size of the resulting tree? If $\hat{\theta}(S, v^*) \approx \theta(S, v^*)$ will we get a near-minimum-size tree?

Question 2: How can we get a good estimate $\hat{\theta}$? Not clear since obtaining samples with true supervised labels $\theta(S, v^*)$ is not computationally viable

QUALITY OF AN ESTIMATE

We assume $\theta(S, v^*) = \hat{\theta}(S, v^*) + r_{\hat{\theta}}(S, v^*)$ where $r_{\hat{\theta}}(S, v^*) \sim N(0, \sigma^2)$

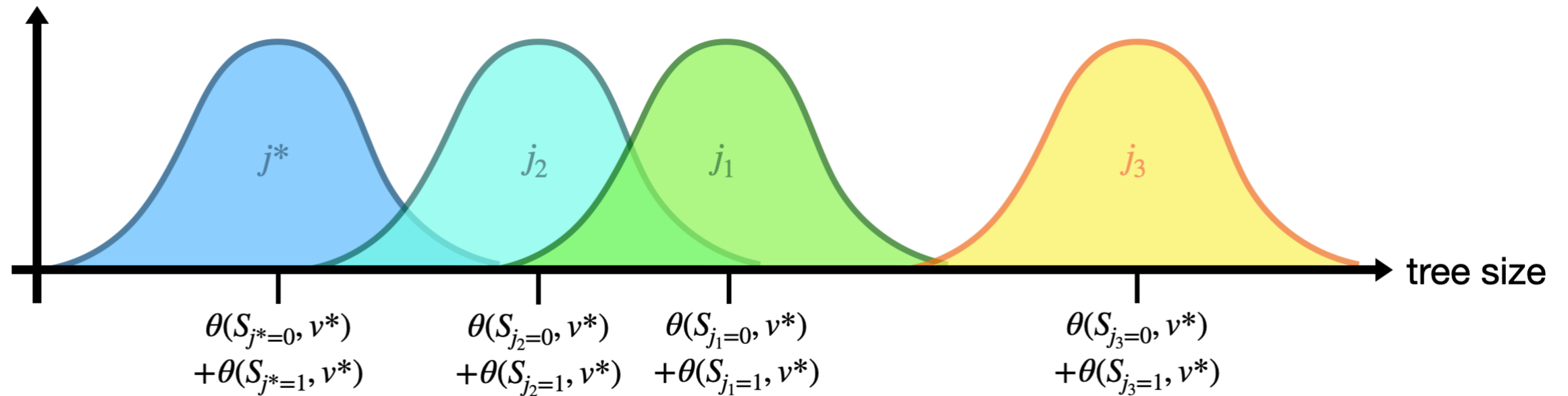
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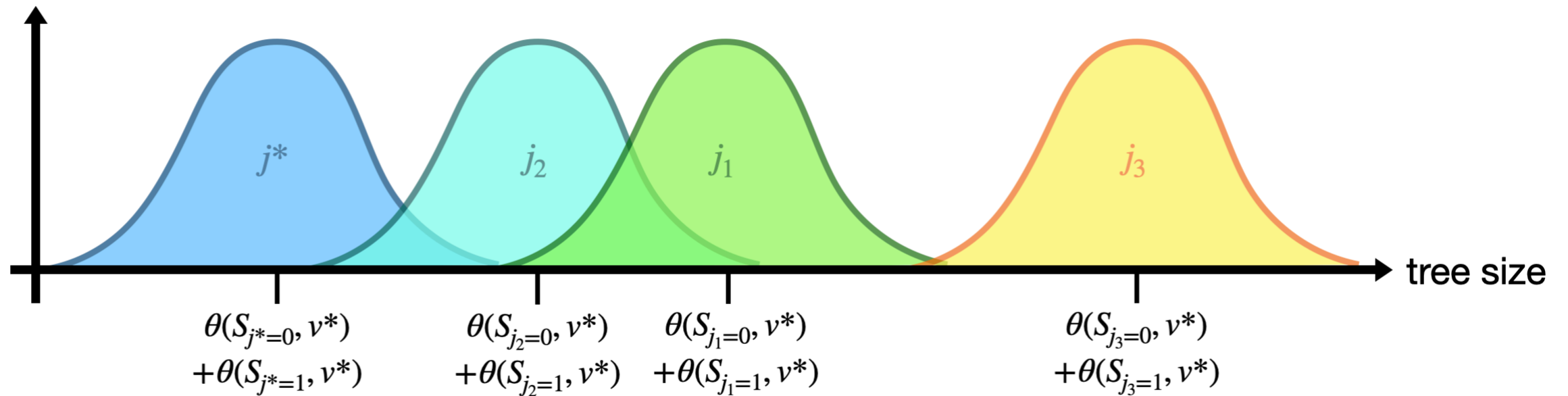
$$\epsilon_{\hat{\theta}}(S, v^*) = \theta(S_{j'=0}) + \theta(S_{j'=1}) - \min_{j \in [n]} \left[\theta(S_{j=0}) + \theta(S_{j=1}) \right]$$

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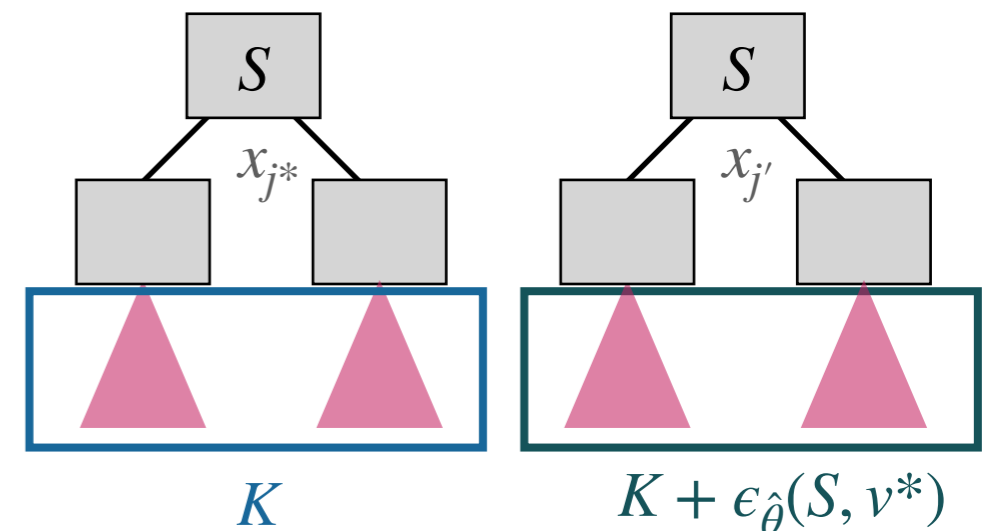
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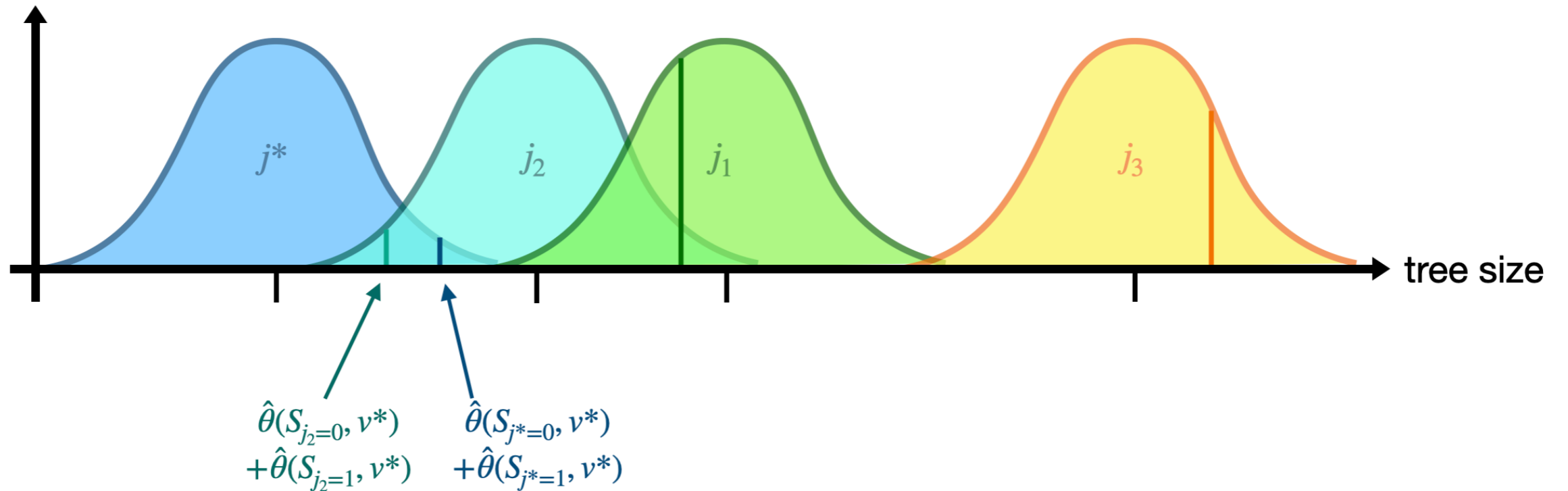
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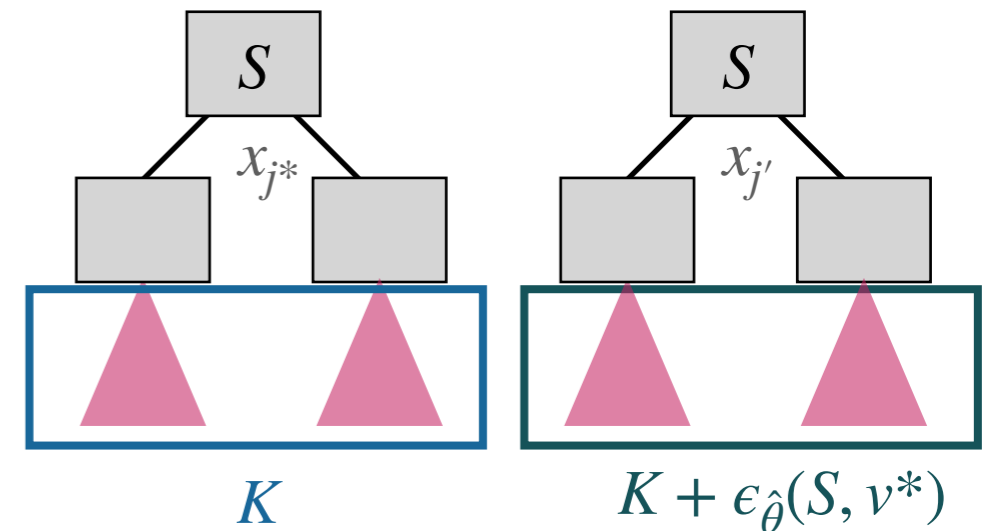
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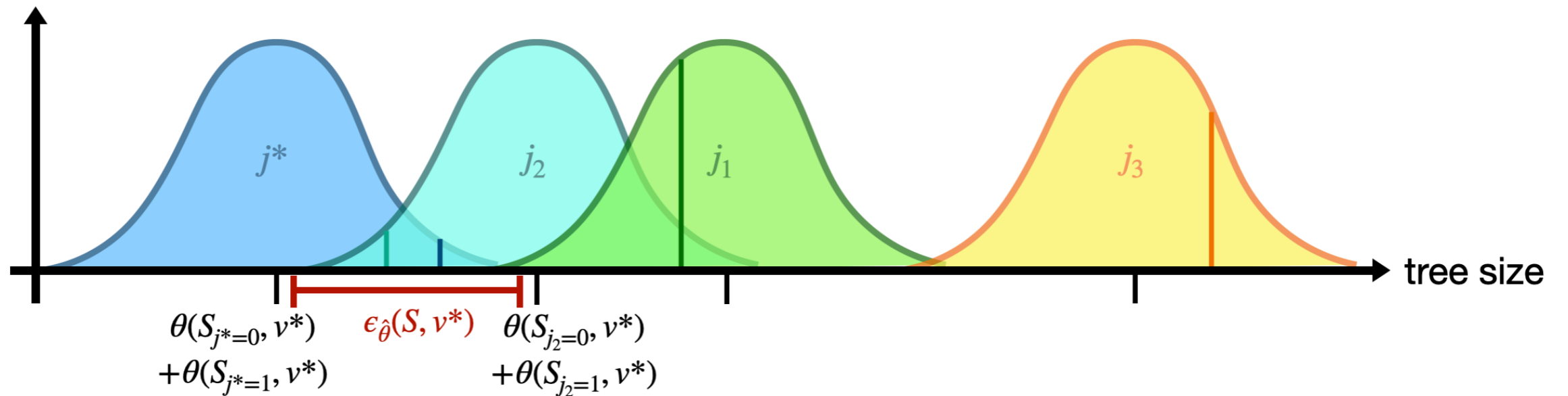
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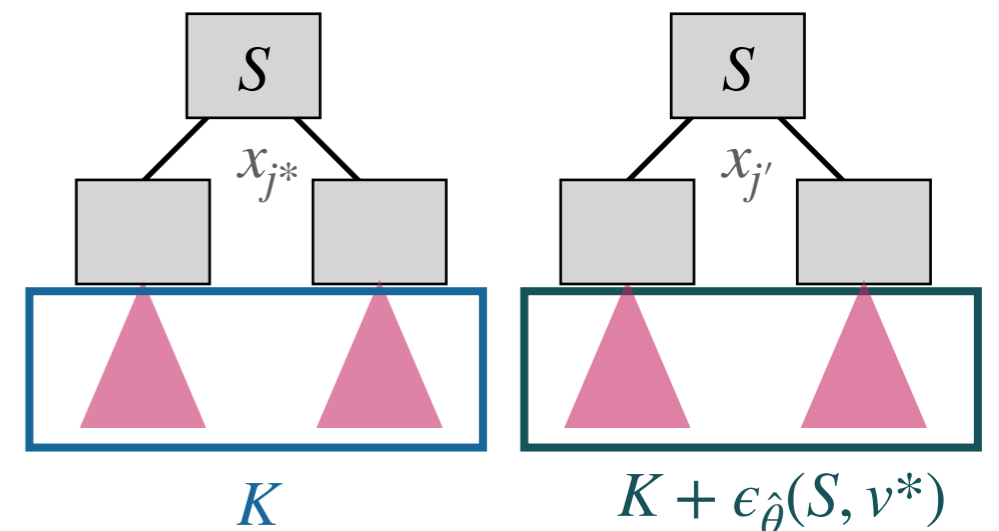
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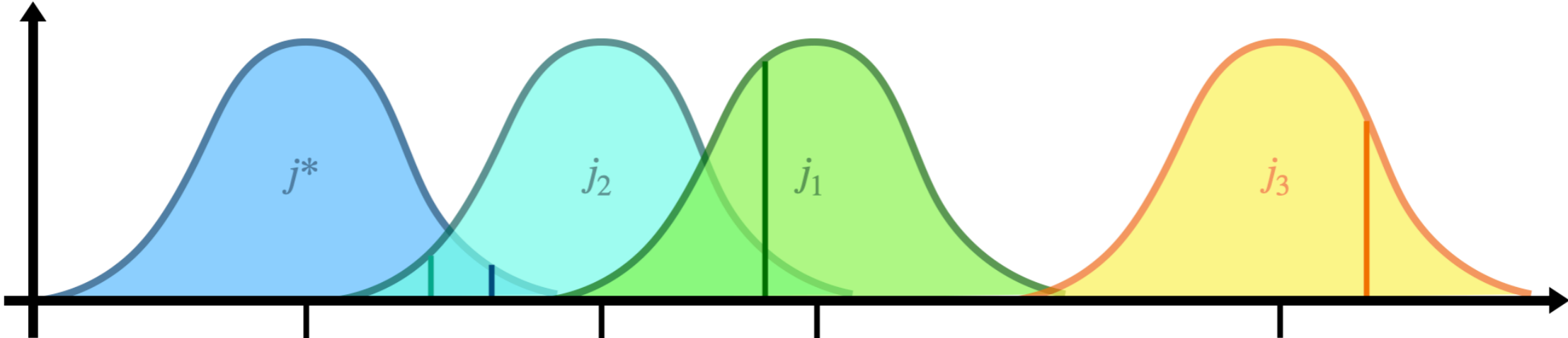
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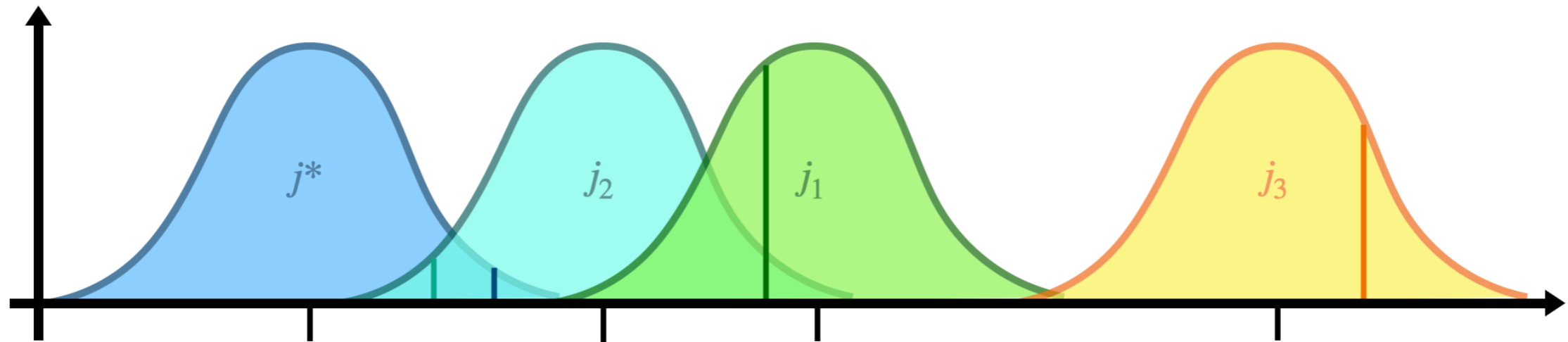
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BETTER ESTIMATES MEAN SMALLER TREES



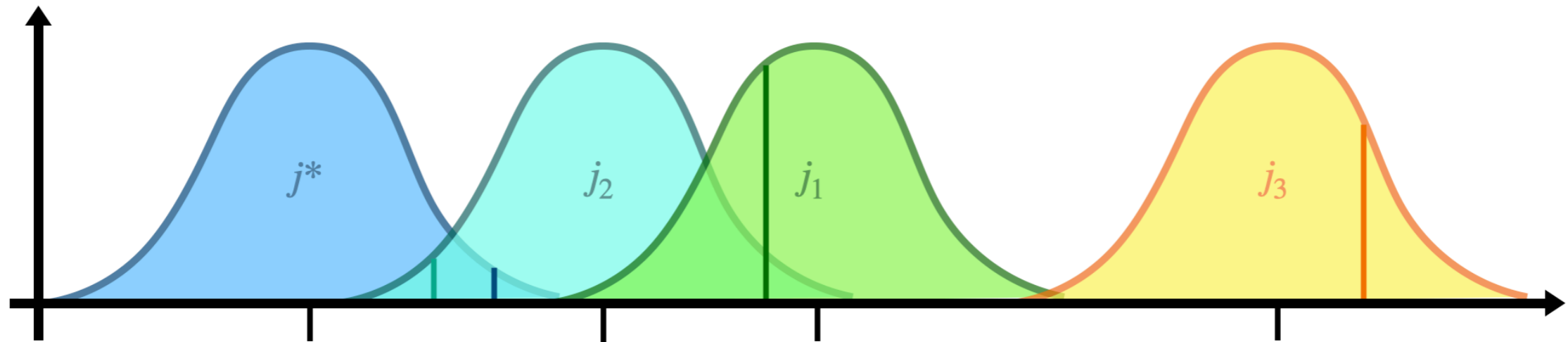
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Proposition (D.)

Let $\hat{\theta}_1, \hat{\theta}_2$ be estimates such that $r_{\hat{\theta}_1}(S, v^*) \sim N(0, \sigma_1^2)$ and $r_{\hat{\theta}_2}(S, v^*) \sim N(0, \sigma_2^2)$ with $\sigma_2 > \sigma_1$. Then, $\mathbb{E} \left[\epsilon_{\hat{\theta}_2}(S, v^*) \right] > \mathbb{E} \left[\epsilon_{\hat{\theta}_1}(S, v^*) \right]$.

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Theorem (D.)

Let $\hat{\theta}$ be such that $\mathbb{E} \left[\epsilon_{\hat{\theta}}(S, v^*) \right] = \alpha \theta(S, v^*)$, where $\alpha \in [0, 1]$, for all possible subproblems S , and let $\mathcal{T}_{\hat{\theta}}(P, v^*)$ be the BB tree certifying bound v^* for the integer program P that branches according to $\hat{\theta}$. Then, $\mathbb{E} \left[|\mathcal{T}_{\hat{\theta}}(P, v^*)| \right] = (1 + \alpha)^n \theta(P, v^*)$.

ESTIMATING A SIGNAL

We settle for an estimate of a more easily computable, accurate signal $\hat{\theta} \approx \theta_{signal} \approx \theta$

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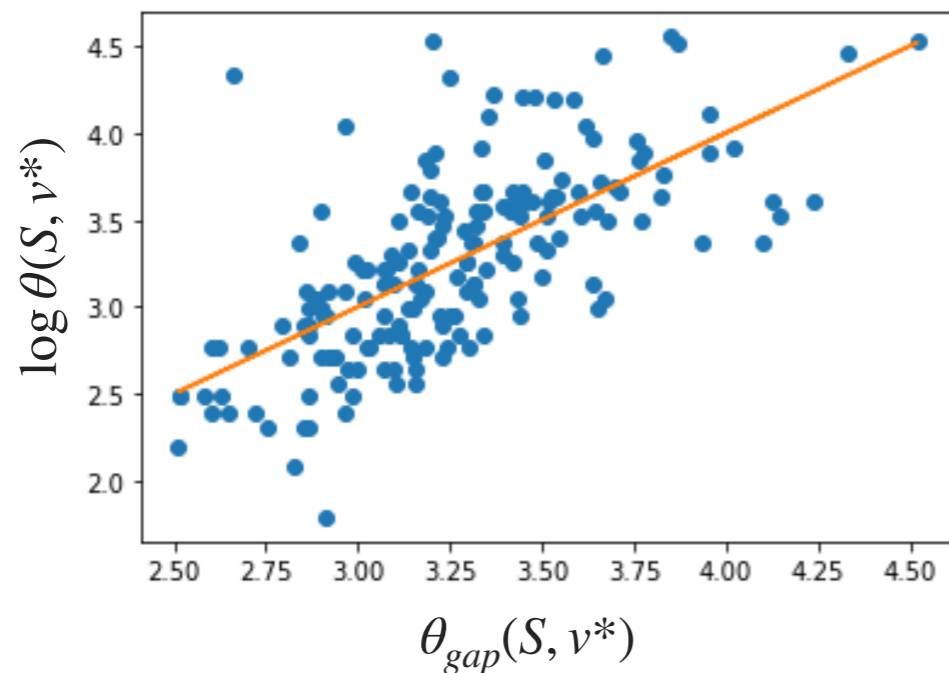
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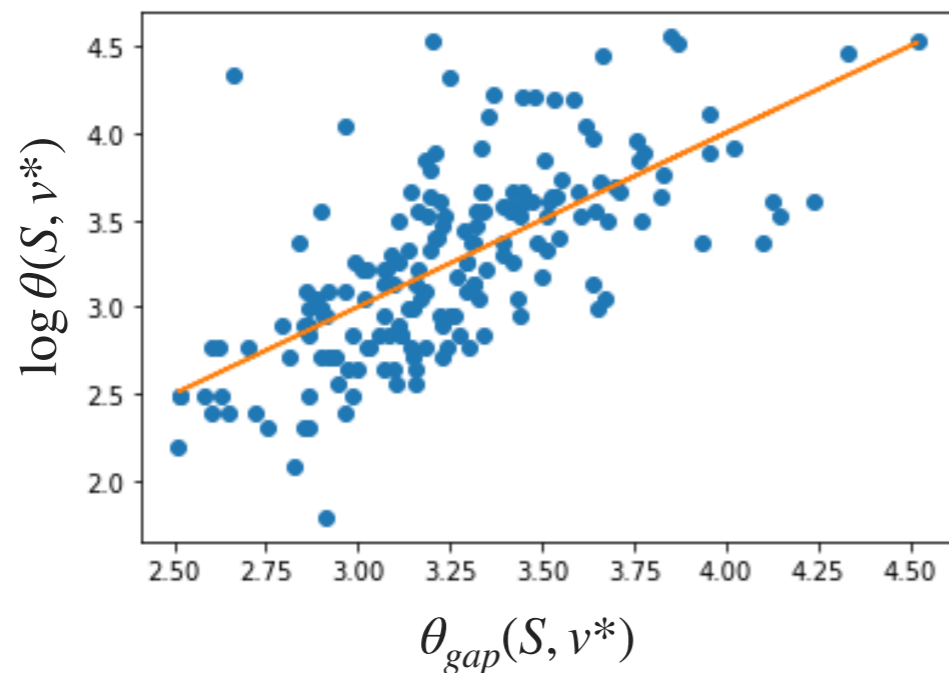
$$r_{\theta_{\text{gap}}}(S, v^*) \sim N(0, 0.4018^2)$$

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We propose two other signals:

$$\theta_{mostinf}(S, v^*) = f(|\mathcal{T}_{mostinf}(S, v^*)|)$$

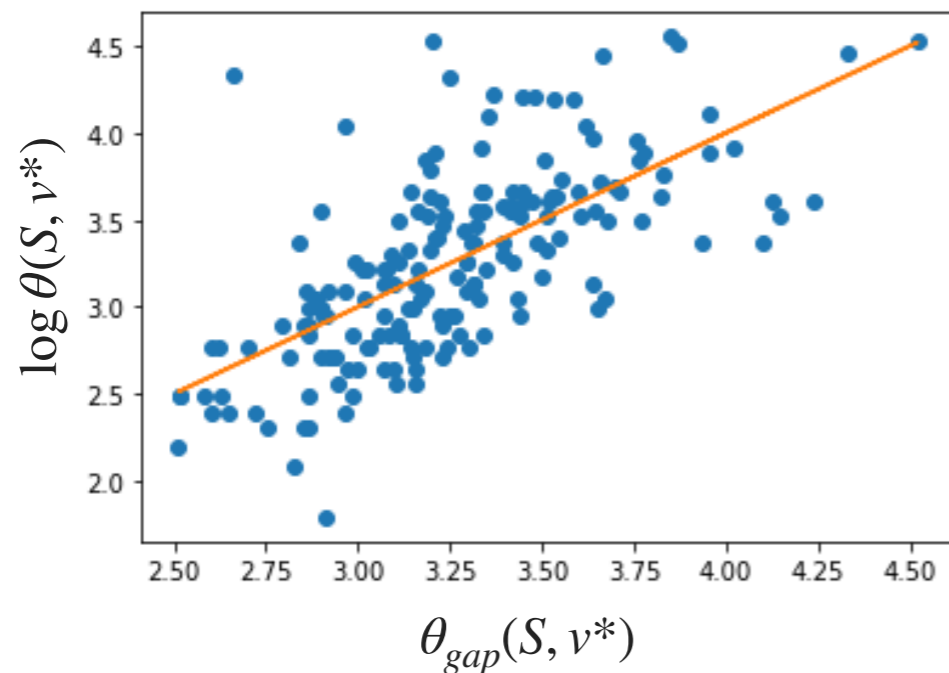
$$\theta_{sb}(S, v^*) = f(|\mathcal{T}_{sb}(S, v^*)|)$$

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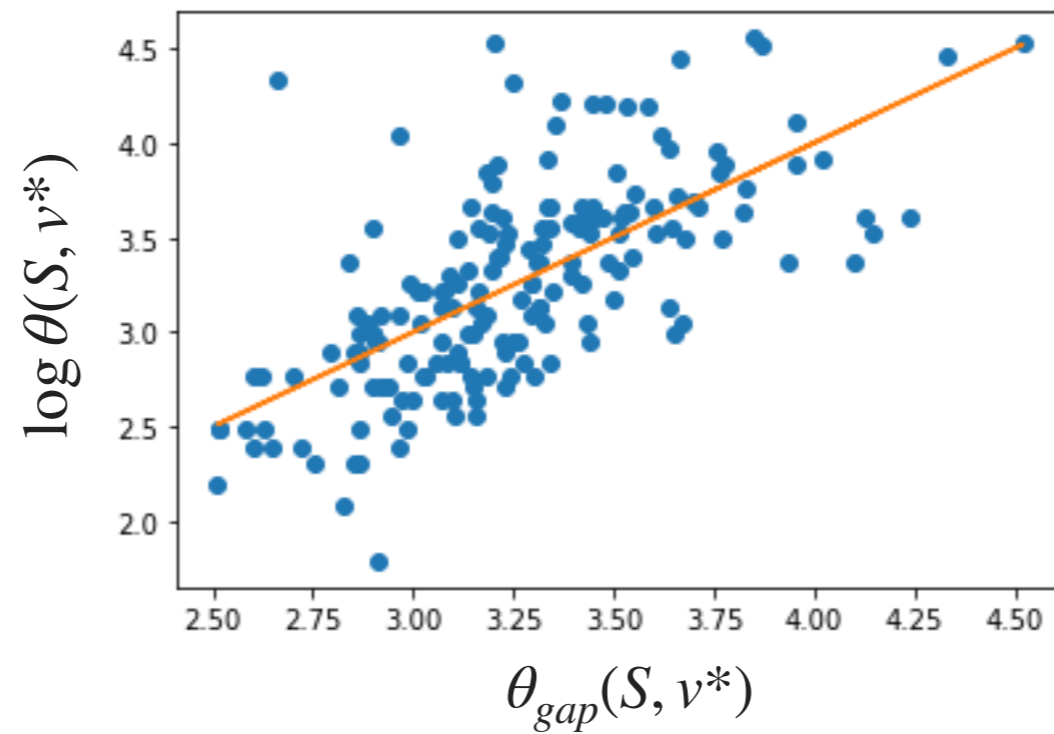
Disclaimer: This data comes from random multi-dimensional knapsack problems, where strong branching is known to struggle

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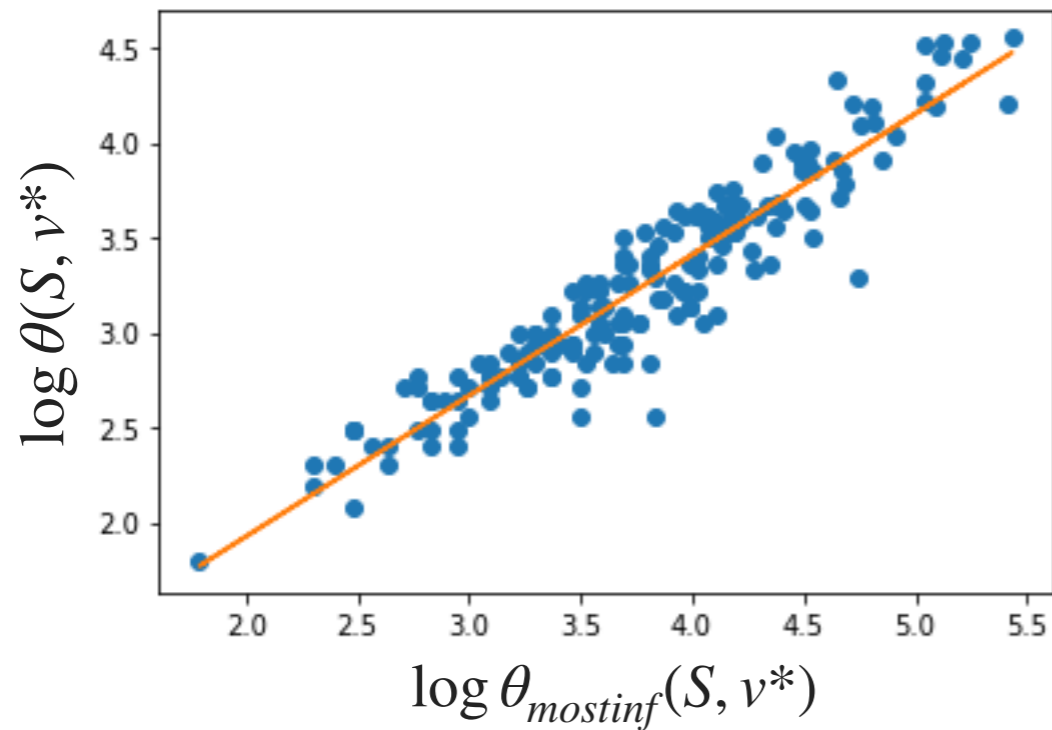
$$\theta_{mostinf}(S, v^*) = f(|\mathcal{T}_{mostinf}(S, v^*)|)$$

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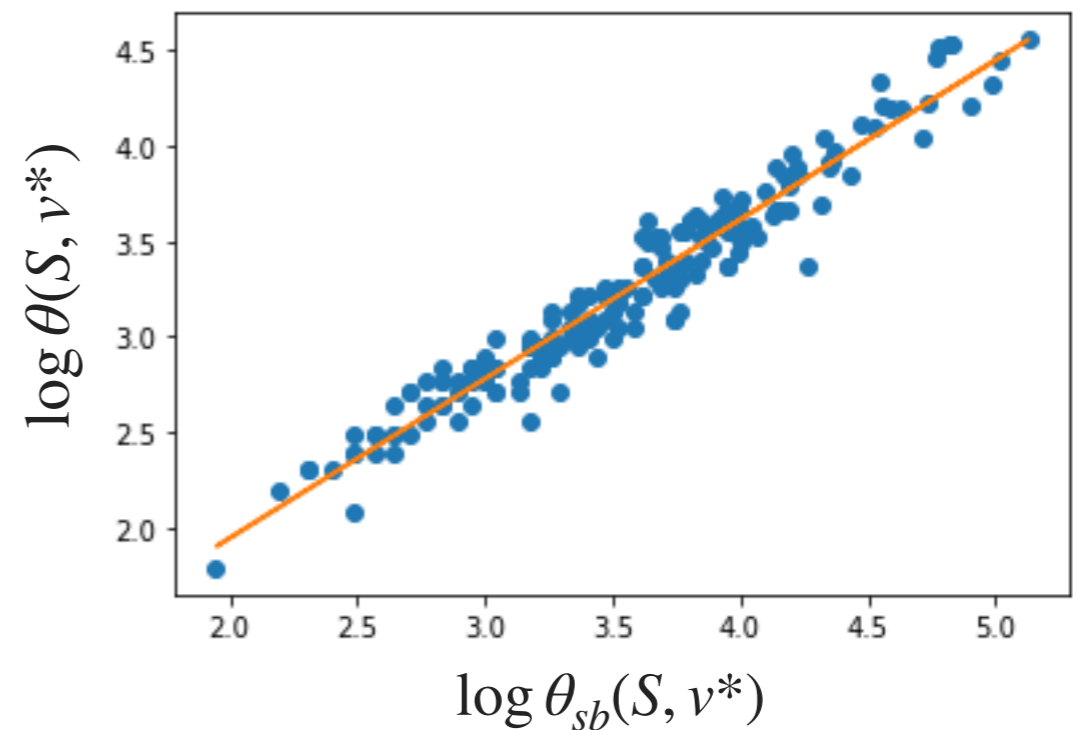
IMPERFECT, BUT GOOD SIGNALS



$$r_{\theta_{gap}}(S, v^*) \sim N(0, 0.4018^2)$$



$$r_{\theta_{mostinf}}(S, v^*) \sim N(0, 0.1842^2)$$



$$r_{\theta_{sb}}(S, v^*) \sim N(0, 0.1286^2)$$

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e.g., branching according to $\theta_{mostinf}$:

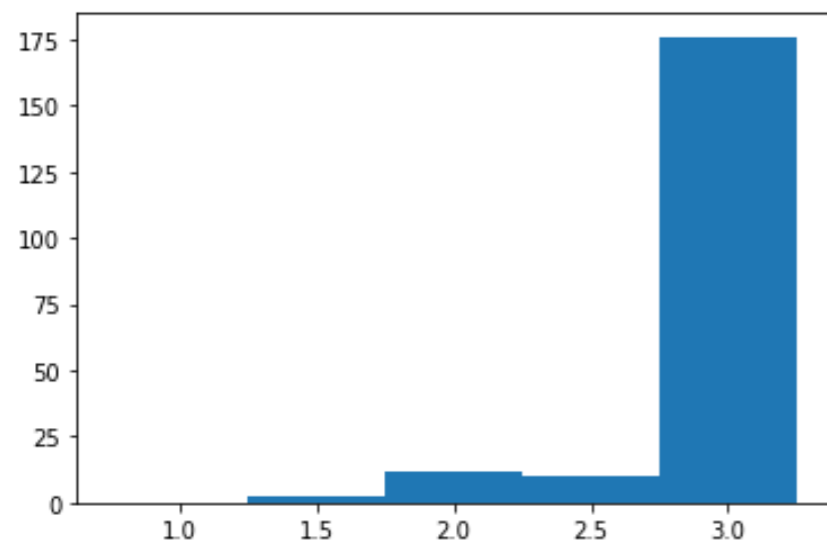
At subproblem S , branch on the variable $\arg \min_{j \in [n]} | \mathcal{T}_{mostinf}(S_{j=0}, v^*) | + | \mathcal{T}_{mostinf}(S_{j=1}, v^*) |$

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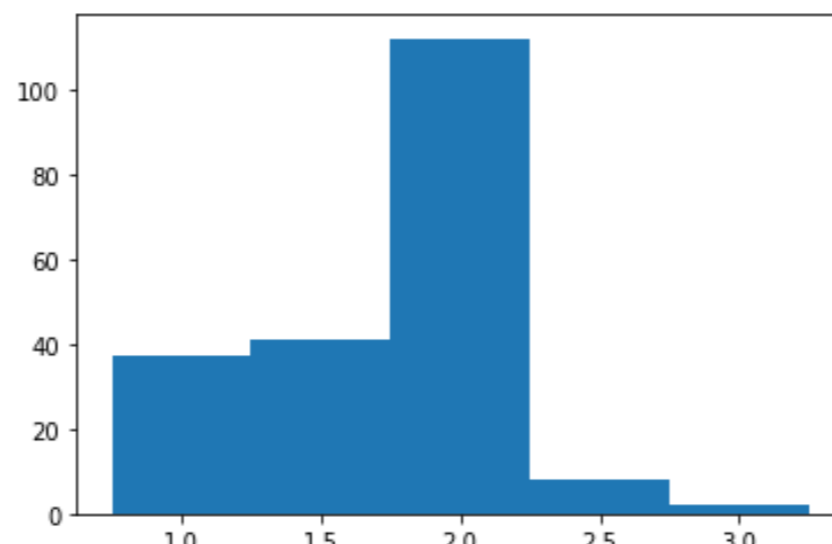
Indeed, we see that the BB trees branching according to these stronger signals are significantly smaller than those produced by strong branching

	geomean +/- geostd
$ \mathcal{T}_{strong} $	37.44 +/- 1.91
$ \mathcal{T}_{\theta_{mostinf}} $	28.83 +/- 1.74
$ \mathcal{T}_{\theta_{sb}} $	27.68 +/- 1.71

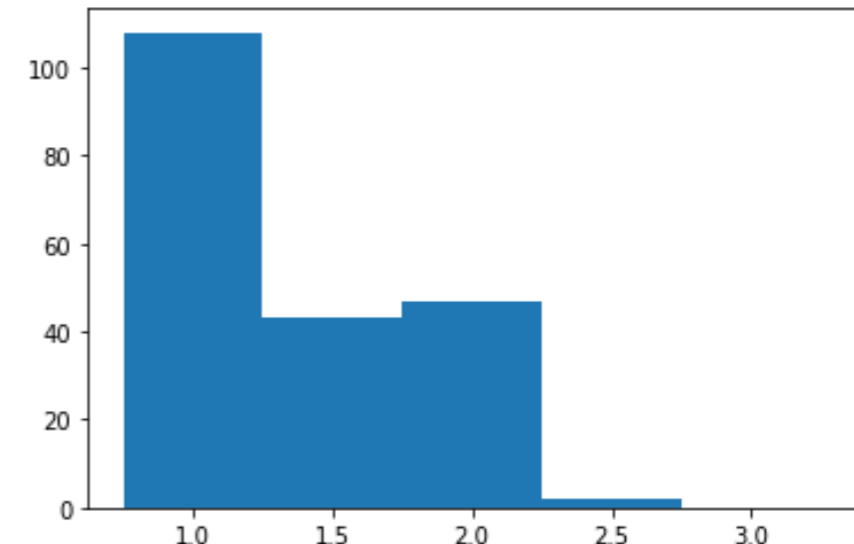
RELATIVE RANKING — FREQUENCY



\mathcal{T}_{strong}



$\mathcal{T}_{\theta_{mostinf}}$



$\mathcal{T}_{\theta_{sb}}$

A MODERATE STRESS TEST

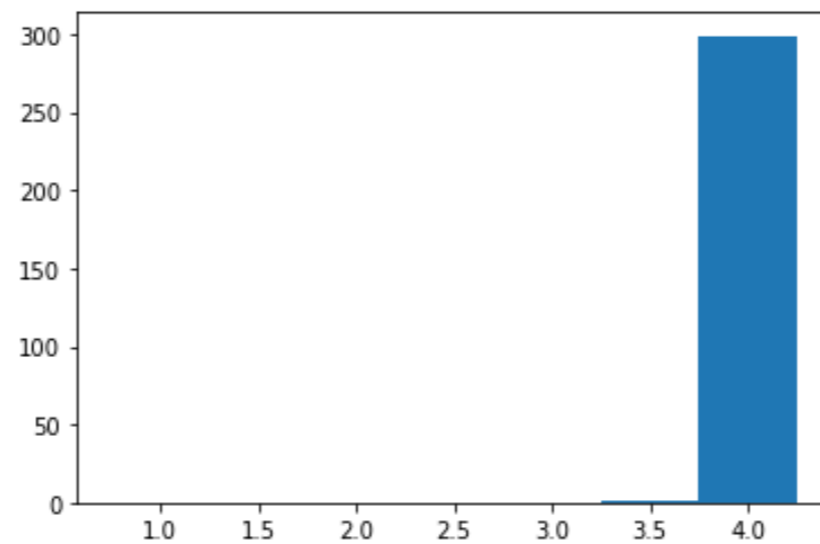
BB trees branching according to these stronger signals are significantly smaller than those produced by strong branching **even when strong branching is excellent**

Data:

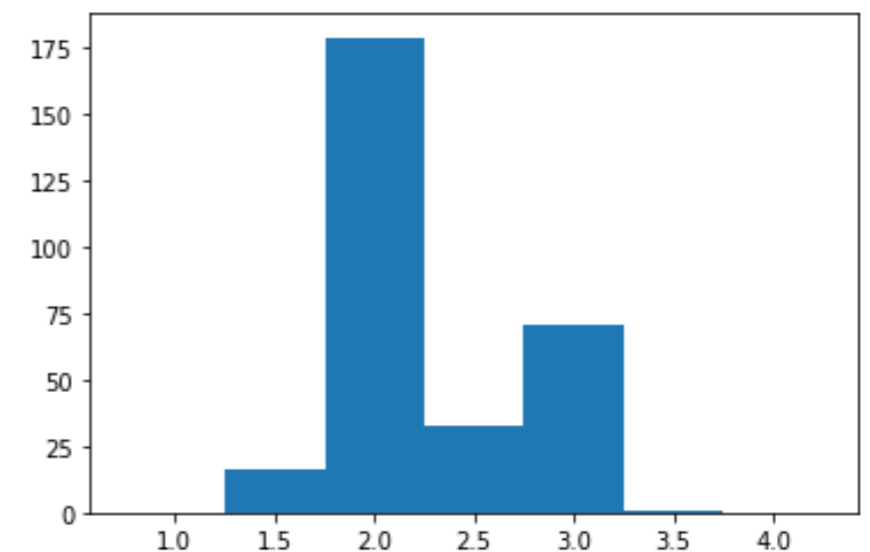
Randomly generated max stable set problems on Albert-Barabasi graphs (100 nodes, affinity=8)

Clique cover relaxation

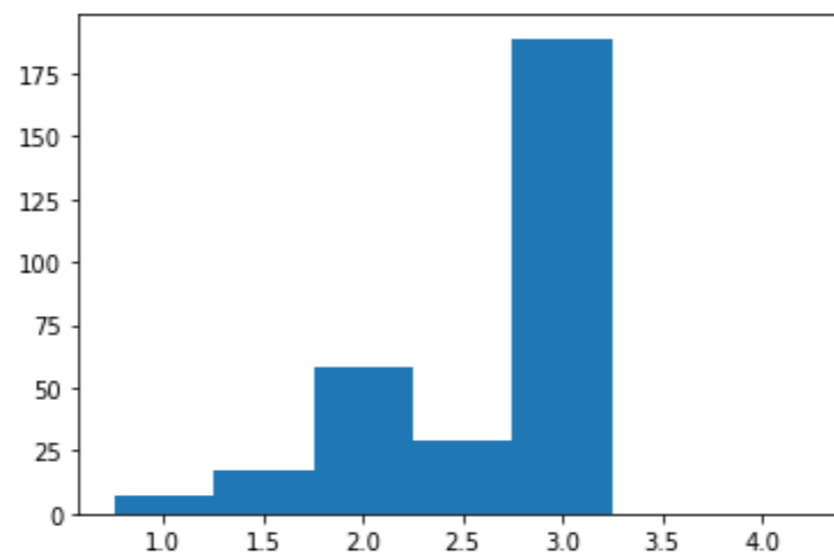
RELATIVE RANKING — FREQUENCY



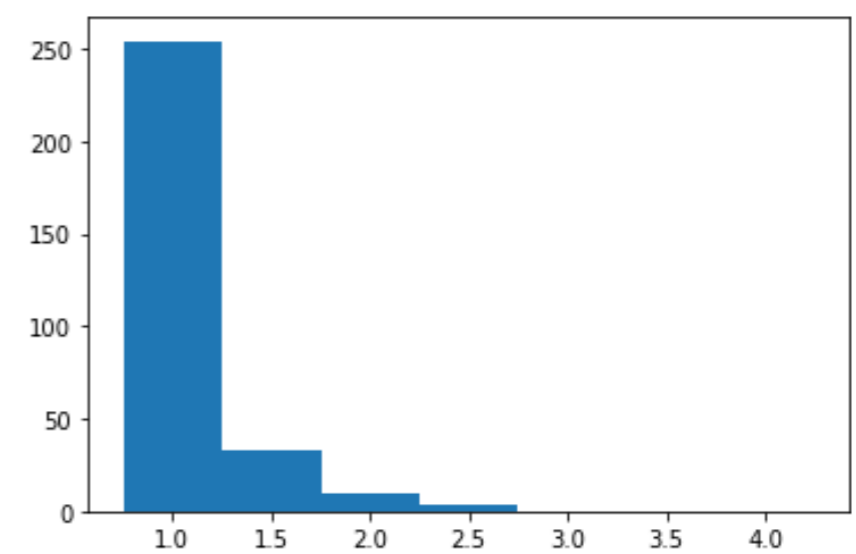
$\mathcal{T}_{mostinf}$



\mathcal{T}_{strong}



$\mathcal{T}_{\theta_{mostinf}}$



$\mathcal{T}_{\theta_{reliability}}$

geomean +/- geostd

$ \mathcal{T}_{mostinf} $	135.69 +/- 2.69
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$ \mathcal{T}_{strong} $	18.39 +/- 2.08
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$ \mathcal{T}_{\theta_{mostinf}} $	21.25 +/- 2.25
------------------------------------	----------------

$ \mathcal{T}_{\theta_{reliability}} $	14.14 +/- 1.99
--	----------------

RECAP, SO FAR

Most of the successful ML for BB research aims to approximate (with ML) the signal θ_{gap} with some learned estimate $\hat{\theta}_{gap}$

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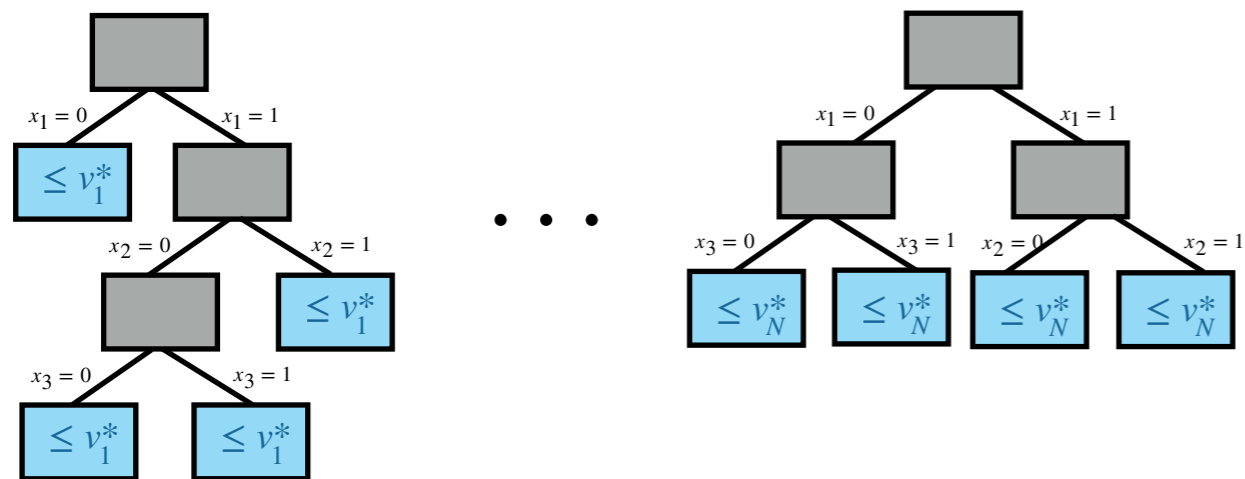
We propose the estimation of a signal that better approximates θ , e.g., we can get realizations of the signals $\theta_{reliability}$ from previous solves using reliability branching

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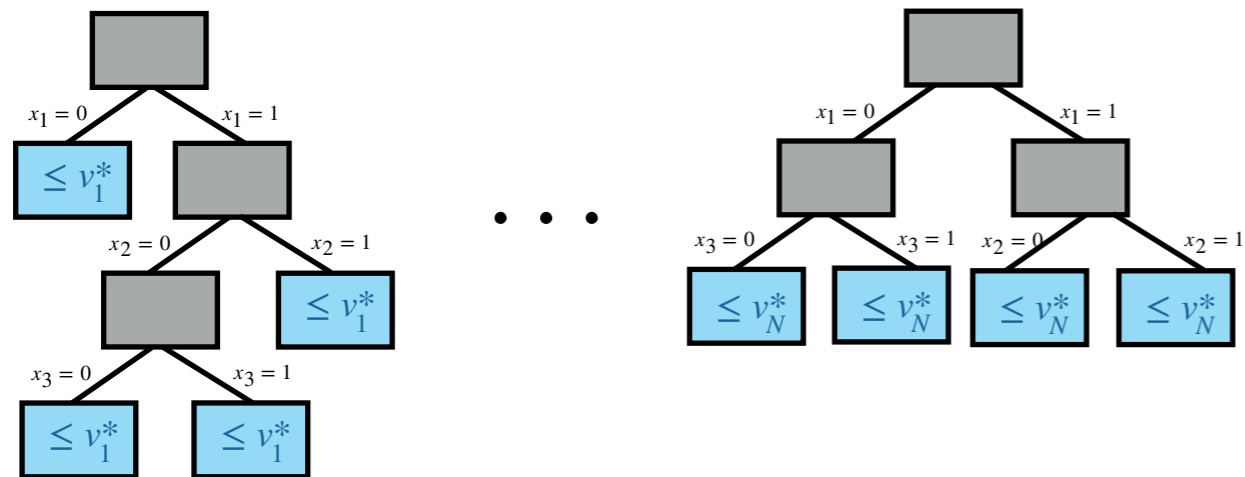


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$$(\Phi(S_1, v_1^*) \quad \theta_{rule}(S_1, v_1^*))$$

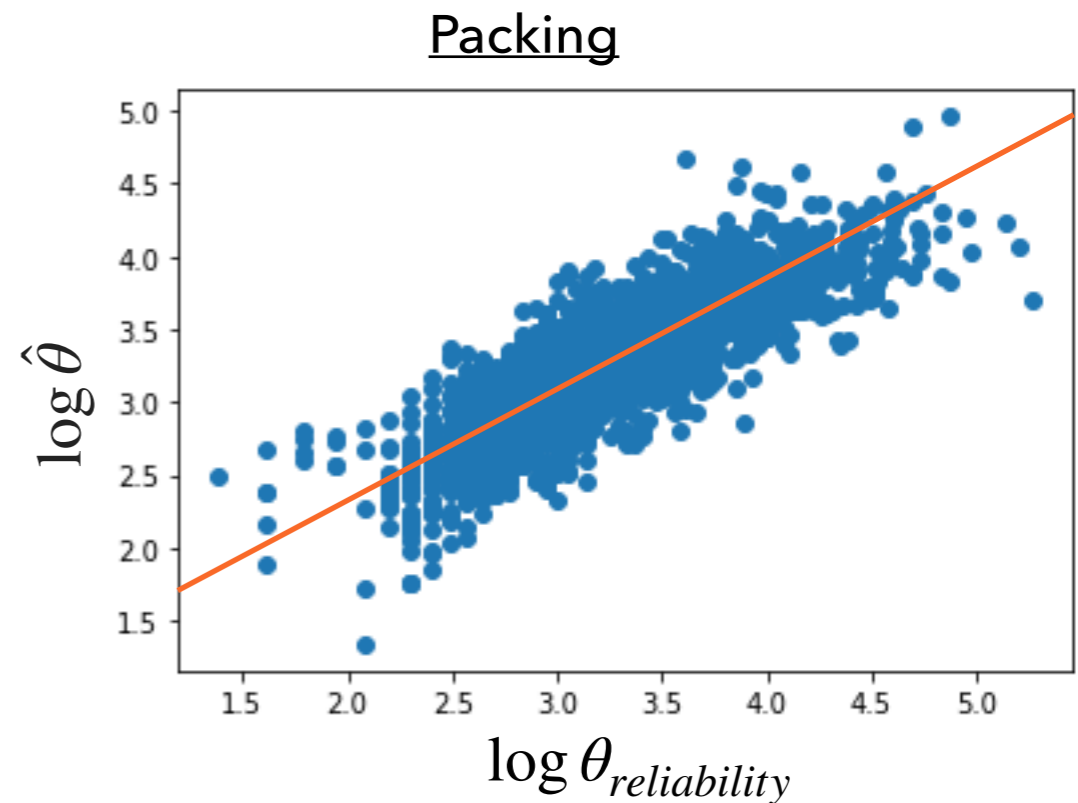
$$(\Phi(S_N, v_N^*) \quad \theta_{rule}(S_N, v_N^*))$$

ESTIMATING PROBLEM DIFFICULTY WITH REGRESSION

$$\hat{\theta}(S, v^*) = \beta_{gap}(f(v(S) - v^*))$$

+ β_{frac} (fractionality of optimal LP solution)

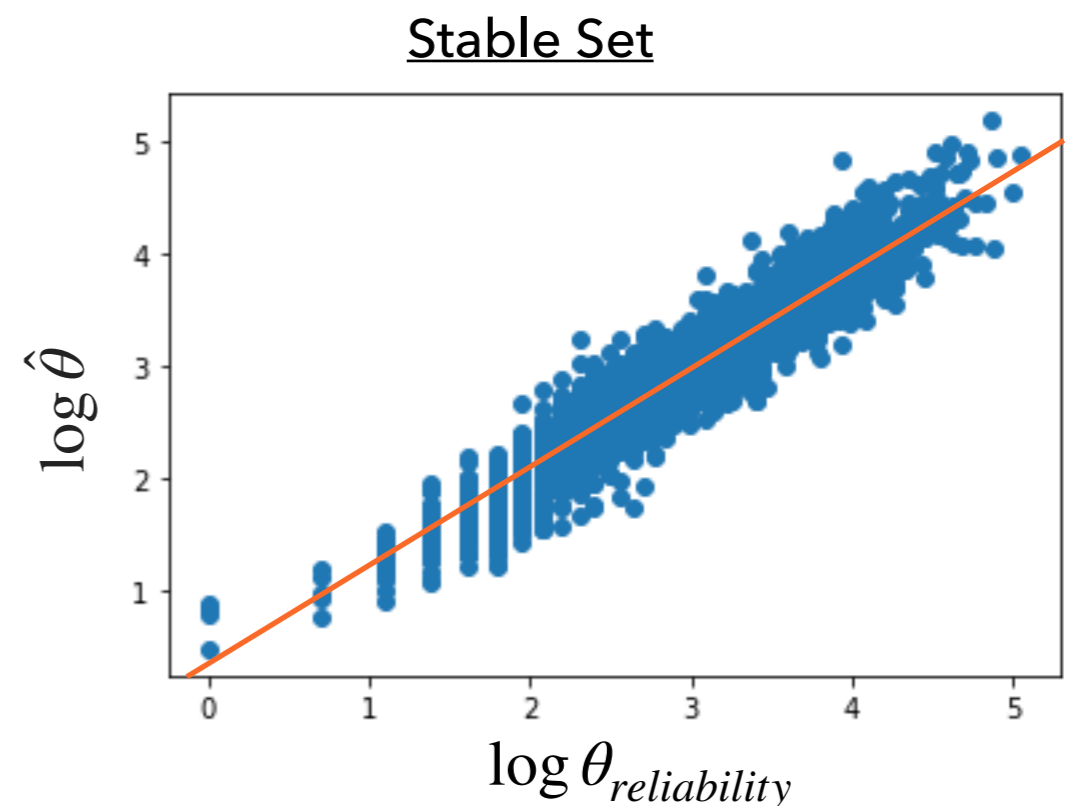
+ β_{dual} (dual information)



$$\hat{\theta}(S, v^*) = \beta_{gap}(f(v(S) - v^*))$$

+ β_{frac} (fractionality of optimal LP solution)

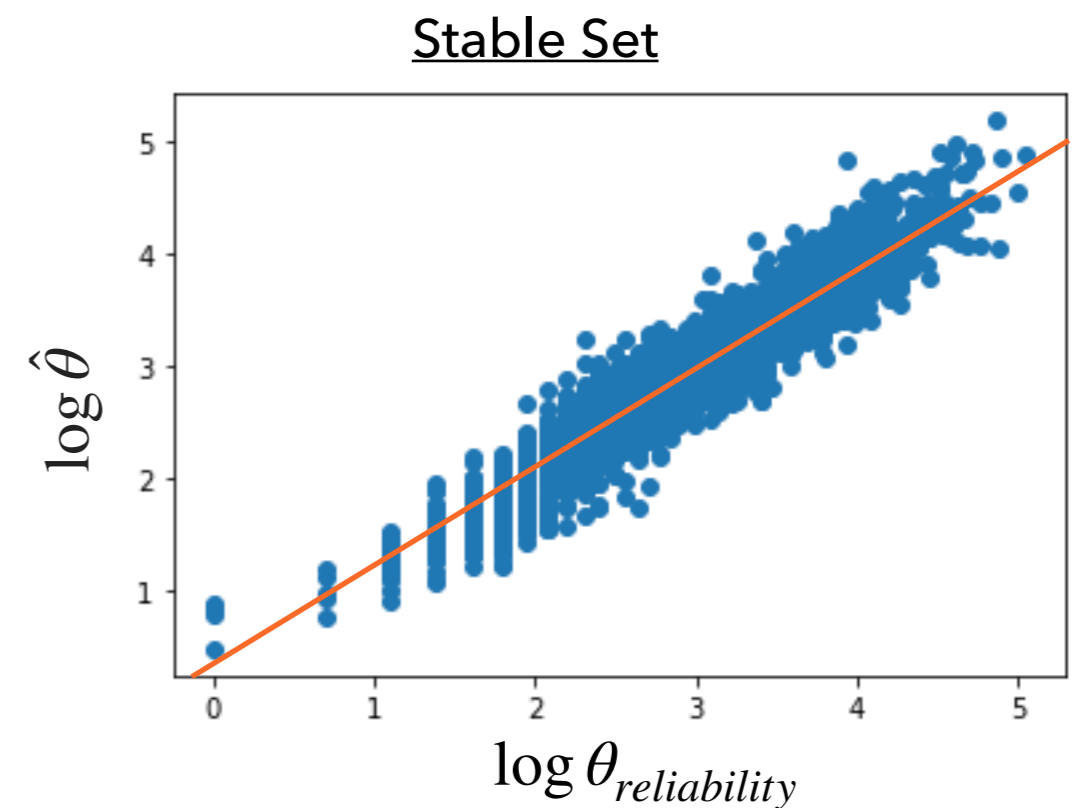
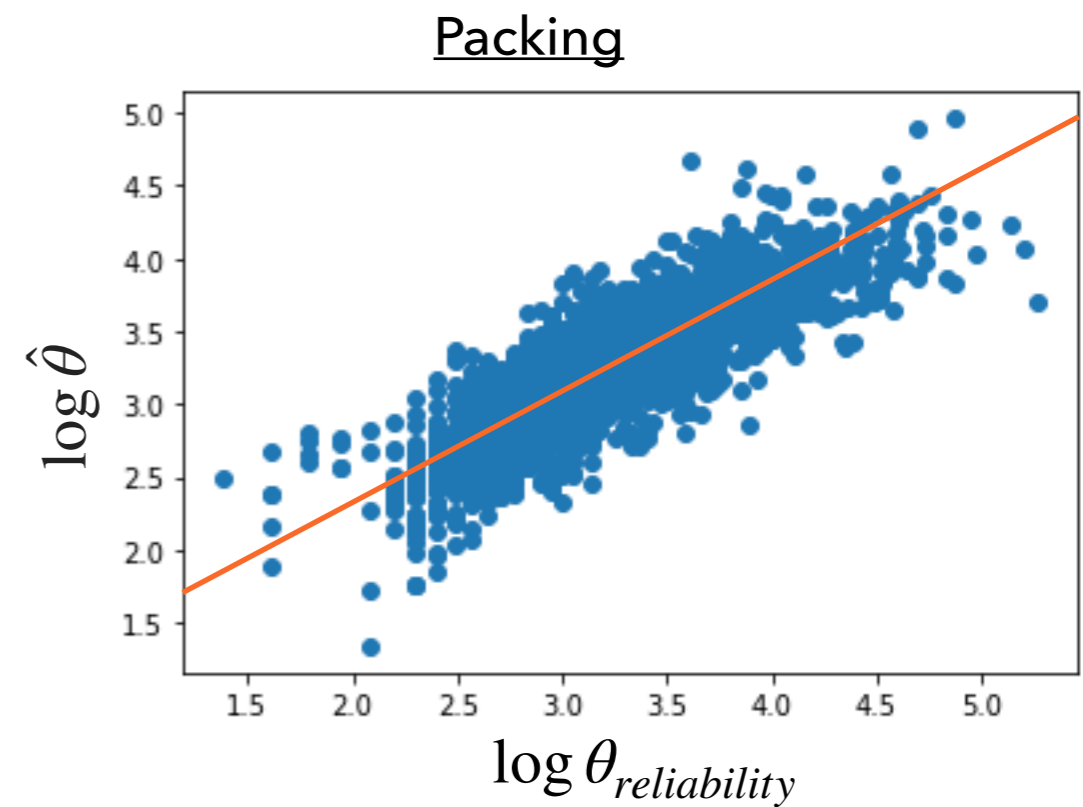
+ β_{graph} (variable-constraint interaction)



BRANCHING ACCORDING TO ESTIMATES

	geomean +/- geostd
$ \mathcal{T}_{strong} $	37.13 +/- 1.92
$ \mathcal{T}_{\hat{\theta}} $	29.48 +/- 1.73
	% won
$ \mathcal{T}_{strong} $	3%
$ \mathcal{T}_{\hat{\theta}} $	96%

	geomean +/- geostd
$ \mathcal{T}_{strong} $	18.44 +/- 2.08
$ \mathcal{T}_{\hat{\theta}} $	17.82 +/- 2.21
	% won
$ \mathcal{T}_{strong} $	32%
$ \mathcal{T}_{\hat{\theta}} $	51%



QUESTIONS?

	geom
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